

How runtime systems can support resource awareness in HPC: the HPX case

Tommaso Bianucci

Technische Universität München

22 June 2018

Exascale will be hard

- ▶ 1 ExaFLOPS = 10^{18} FLOPS
- ▶ Billions of cores?
- ▶ Etherogeneous hardware
 - ▶ Manycore CPUs
 - ▶ GPUs
 - ▶ FPGAs

→ These machines expose an extreme degree of parallelism.

Exascale will be hard

- ▶ 1 ExaFLOPS = 10^{18} FLOPS
 - ▶ Billions of cores?
 - ▶ Etherogeneous hardware
 - ▶ Manycore CPUs
 - ▶ GPUs
 - ▶ FPGAs
- These machines expose an extreme degree of parallelism.

Applications are hard

- ▶ *Scaling-impaired* applications
- ▶ Unbalanced execution tree

This causes:

- ▶ Poor parallel performance
- ▶ Suboptimal resource usage

→ Some applications do not scale well.

Applications are hard

- ▶ *Scaling-impaired* applications
- ▶ Unbalanced execution tree

This causes:

- ▶ Poor parallel performance
- ▶ Suboptimal resource usage

→ Some applications do not scale well.

Applications are hard

- ▶ *Scaling-impaired* applications
- ▶ Unbalanced execution tree

This causes:

- ▶ Poor parallel performance
- ▶ Suboptimal resource usage

→ Some applications do not scale well.

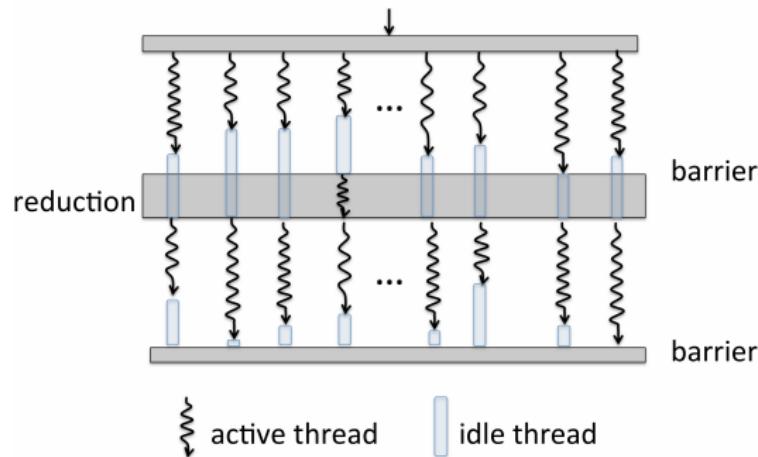
Programming model matters

Current predominant model in HPC:

- ▶ *Fork-join* for shared memory (OpenMP)
- ▶ *Communicating Sequential Processes* for distributed memory (MPI)

Problems:

- ▶ Global barriers
- ▶ Load imbalance



P.A. Grubel: "Dynamic adaptation in hpx, a task-based parallel runtime system" 2016.

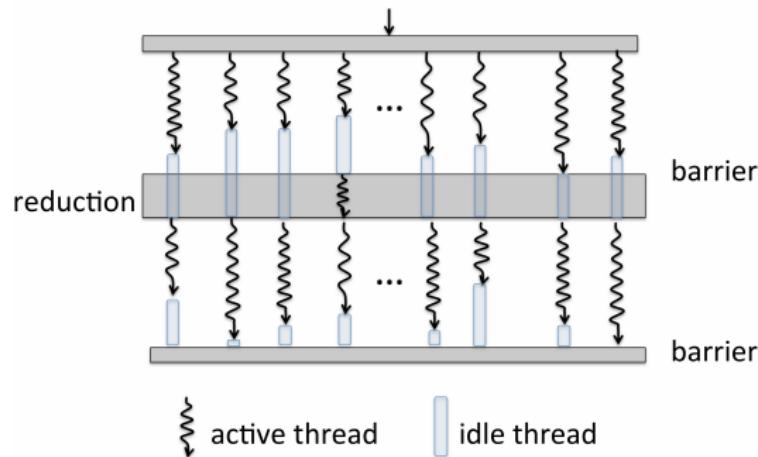
Programming model matters

Current predominant model in HPC:

- ▶ *Fork-join* for shared memory (OpenMP)
- ▶ *Communicating Sequential Processes* for distributed memory (MPI)

Problems:

- ▶ Global barriers
- ▶ Load imbalance



P.A.Gruber: "Dynamic adaptation in hpx, a task-based parallel runtime system" 2016.

Resource awareness: clever software for complex hardware

Resource awareness

- ▶ Adaptive allocation and usage of resources
- ▶ The system is aware of its own resources
- ▶ At runtime vs. before execution

Resource awareness: clever software for complex hardware

Resource awareness

- ▶ Adaptive allocation and usage of resources
- ▶ The system is aware of its own resources
- ▶ At runtime vs. before execution

What are resources?

1. Hardware entities

- ▶ Computational units
- ▶ Memory
- ▶ Bus/network bandwidth
- ▶ I/O devices
- ▶ Power
- ▶ Thermal

2. Software entities

- ▶ Buffers
- ▶ Queues

What are resources?

1. Hardware entities

- ▶ Computational units
- ▶ Memory
- ▶ Bus/network bandwidth
- ▶ I/O devices
- ▶ Power
- ▶ Thermal

2. Software entities

- ▶ Buffers
- ▶ Queues

Different levels of awareness

1. Embedded computing

E.g.: Invasive computing on MPSoC

2. Application/runtime system level

E.g.: load balance, task scheduling

3. Supercomputing facility

E.g.: Invasive MPI + job scheduler integration

Different levels of awareness

1. Embedded computing

E.g.: Invasive computing on MPSoC

2. Application/runtime system level

E.g.: load balance, task scheduling

3. Supercomputing facility

E.g.: Invasive MPI + job scheduler integration

Different levels of awareness

1. Embedded computing
E.g.: Invasive computing on MPSoC
2. Application/runtime system level
E.g.: load balance, task scheduling
3. Supercomputing facility
E.g.: Invasive MPI + job scheduler integration

High Performance paralleX

C++ runtime system for

- ▶ *Task-based parallelism*
- ▶ *Shared memory + Distributed memory parallelization*
- ▶ Fine-grained parallelism

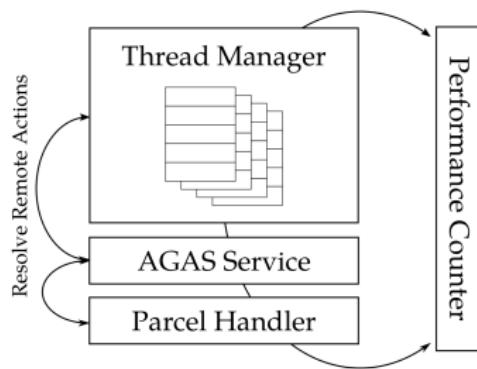
High Performance paralleX

C++ runtime system for

- ▶ *Task-based parallelism*
- ▶ *Shared memory + Distributed memory parallelization*
- ▶ Fine-grained parallelism

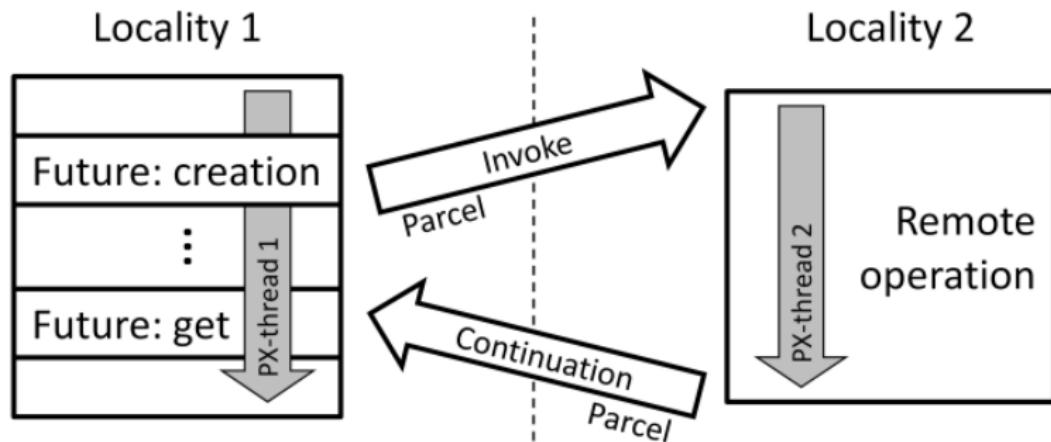
HPX foundations

- ▶ Asynchronous scheduling and execution
- ▶ Lightweight synchronization
- ▶ Active Global Address Space (AGAS)
- ▶ Performance monitoring framework



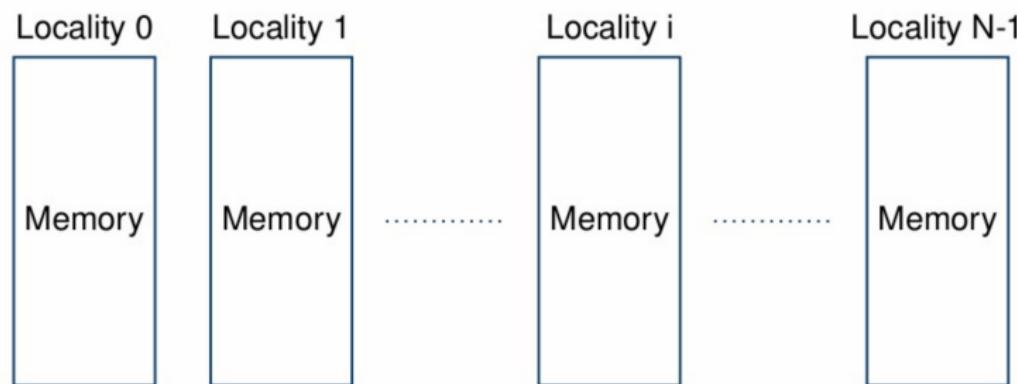
T. Heller et al.: "Hpx – an open source c++ standard library for parallelism and concurrency"
2017.

Futures



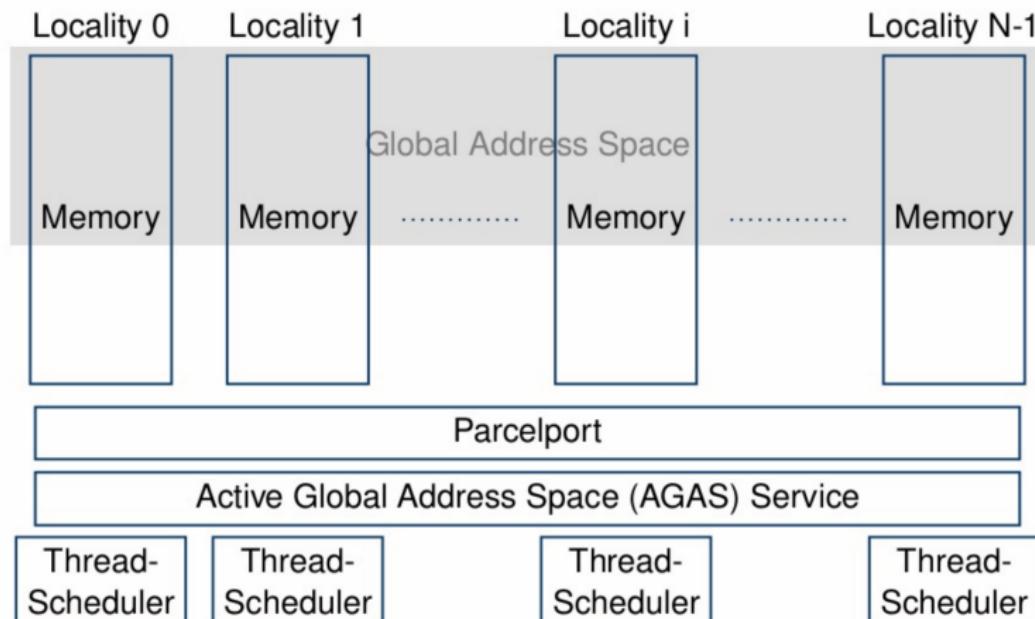
H. Kaiser et al.: "Paralex an advanced parallel execution model for scaling-impaired applications" 2009.

Programming model



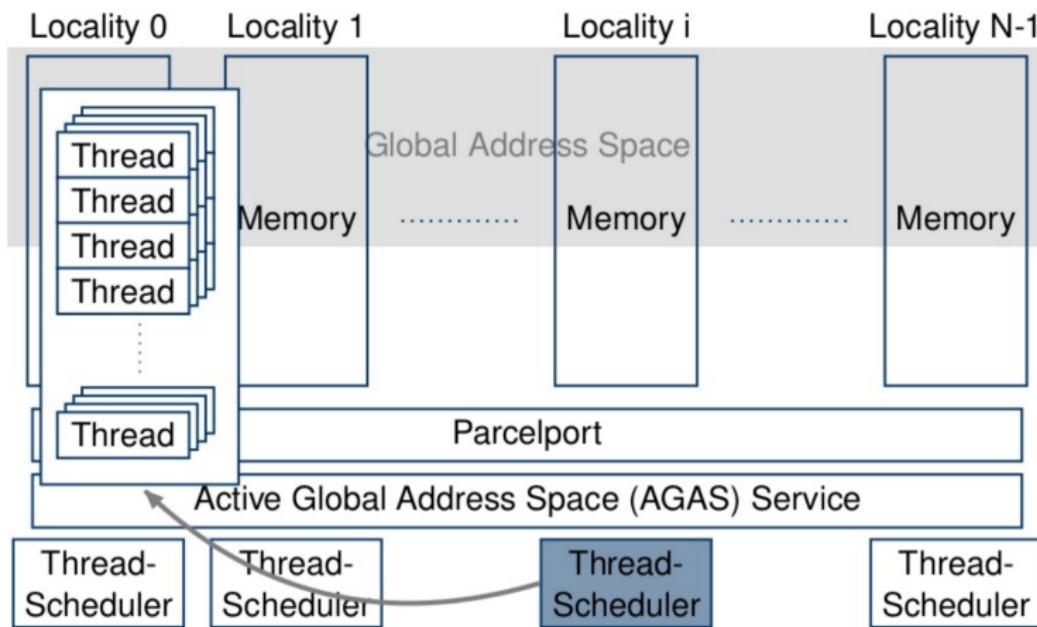
T. Heller: "C++ on its way to exascale and beyond - The HPX Parallel Runtime System" 2016.

Programming model



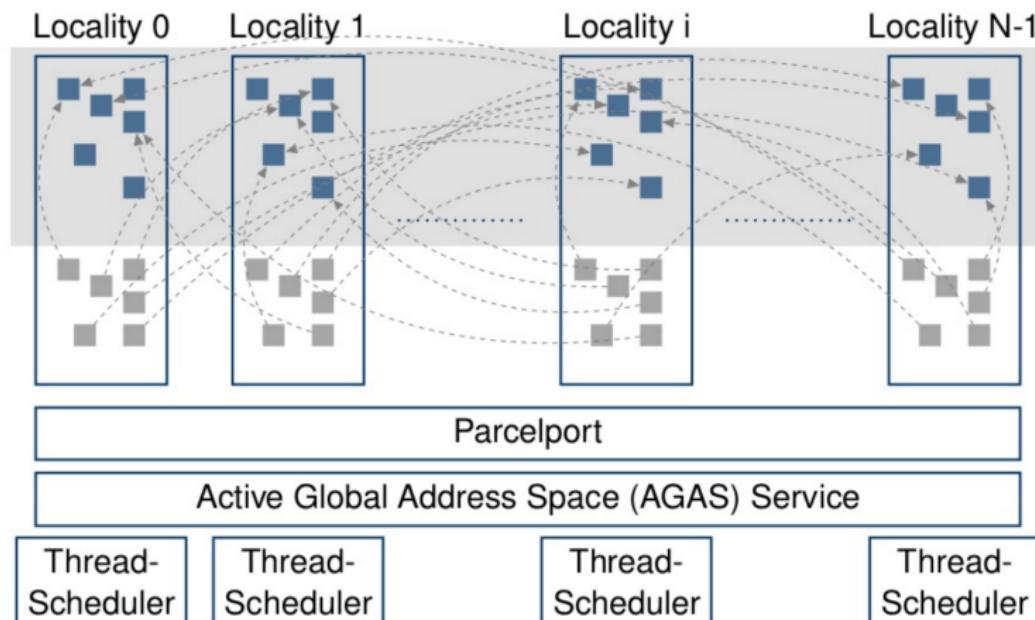
T. Heller: "C++ on its way to exascale and beyond - The HPX Parallel Runtime System" 2016.

Programming model



T. Heller: "C++ on its way to exascale and beyond - The HPX Parallel Runtime System" 2016.

Programming model



T. Heller: "C++ on its way to exascale and beyond - The HPX Parallel Runtime System" 2016.

HPX and Resource Awareness

Capabilities

1. Task scheduling
→ Work stealing + NUMA-awareness
2. AGAS
→ Dynamic relocation of objects
3. Percolation
→ Directly addressing HW accelerators
4. Performance counters
→ Easier integration into applications

HPX and Resource Awareness

Capabilities

1. Task scheduling
→ Work stealing + NUMA-awareness
2. AGAS
→ Dynamic relocation of objects
3. Percolation
→ Directly addressing HW accelerators
4. Performance counters
→ Easier integration into applications

HPX and Resource Awareness

Capabilities

1. Task scheduling

→ Work stealing + NUMA-awareness

2. AGAS

→ Dynamic relocation of objects

3. Percolation

→ Directly addressing HW accelerators

4. Performance counters

→ Easier integration into applications

HPX and Resource Awareness

Capabilities

1. Task scheduling
→ Work stealing + NUMA-awareness
2. AGAS
→ Dynamic relocation of objects
3. Percolation
→ Directly addressing HW accelerators
4. Performance counters
→ Easier integration into applications

HPX and Resource Awareness

Capabilities

1. Task scheduling
→ Work stealing + NUMA-awareness
2. AGAS
→ Dynamic relocation of objects
3. Percolation
→ Directly addressing HW accelerators
4. Performance counters
→ Easier integration into applications

HPX and Resource Awareness (2)

Limitations

1. (An)elasticity of HPX
→ Worker threads and localities cannot be changed at runtime
2. Energy unawareness
→ E.g. no DVFS support
3. Fault tolerance
→ No built-in facility

HPX and Resource Awareness (2)

Limitations

1. (An)elasticity of HPX
→ Worker threads and localities cannot be changed at runtime
2. Energy unawareness
→ E.g. no DVFS support
3. Fault tolerance
→ No built-in facility

HPX and Resource Awareness (2)

Limitations

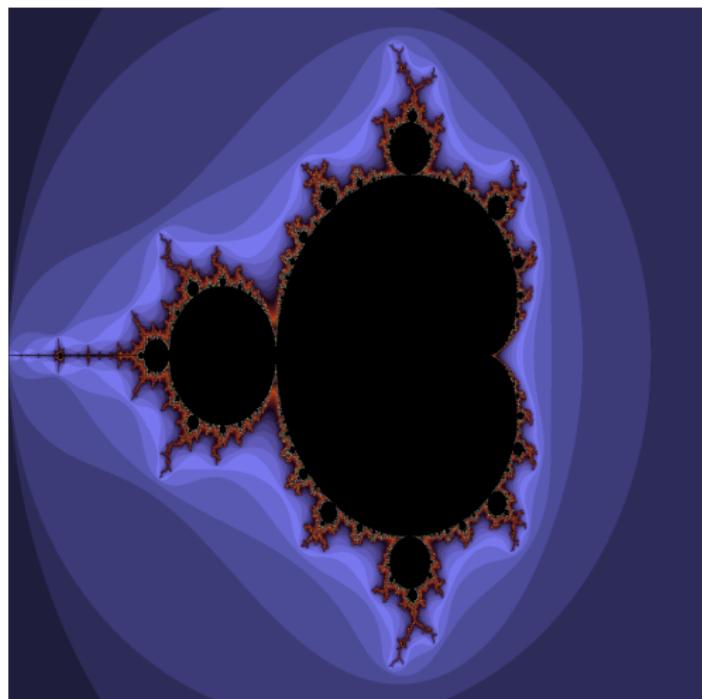
1. (An)elasticity of HPX
→ Worker threads and localities cannot be changed at runtime
2. Energy unawareness
→ E.g. no DVFS support
3. Fault tolerance
→ No built-in facility

HPX coding example: the Mandelbrot set

$$\begin{cases} z_{c,0} &= 0 \\ z_{c,n+1} &= z_{c,n}^2 + c \end{cases}$$

$\mathcal{M} =$

$$\{c \in \mathbb{C} : \lim_{n \rightarrow \infty} |z_{c,n}| < +\infty\}$$

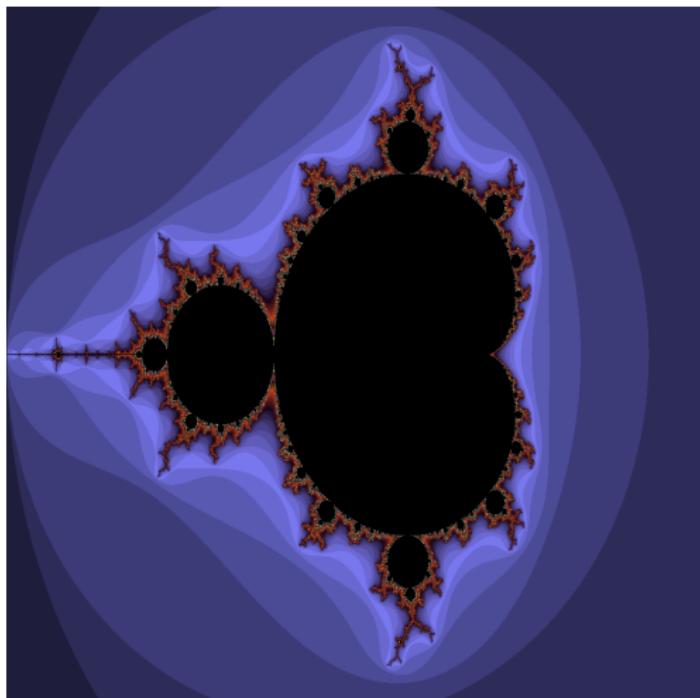


HPX coding example: the Mandelbrot set

$$\begin{cases} z_{c,0} &= 0 \\ z_{c,n+1} &= z_{c,n}^2 + c \end{cases}$$

$\mathcal{M} =$

$$\{c \in \mathbb{C} : \lim_{n \rightarrow \infty} |z_{c,n}| < +\infty\}$$

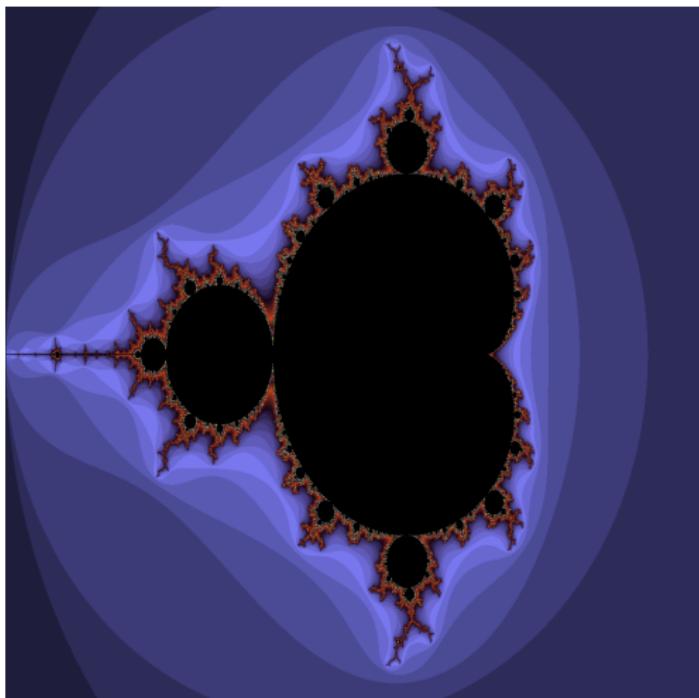


HPX coding example: the Mandelbrot set

$$\begin{cases} z_{c,0} &= 0 \\ z_{c,n+1} &= z_{c,n}^2 + c \end{cases}$$

$\mathcal{M} =$

$$\{c \in \mathbb{C} : \lim_{n \rightarrow \infty} |z_{c,n}| < +\infty\}$$



Mandelbrot: kernel

```
1 void mandelbrot_kernel(int taskNo, staticData *sd) {
2     // Computes one row of the image
3     int i = taskNo;
4     for (int j=0; j < sd->xRes; ++j) {
5         int x = getX(j, sd);
6         int y = getY(i, sd);
7         complex double Z = 0 + 0*I;
8         complex double C = x + y*I;
9
10        int k = 0;
11        do { // Check the convergence of the sequence
12            Z = Z * Z + C;
13            k++;
14        } while (cabs(Z) < 2 && k < max_iter);
15
16        if (k == max_iter) { // In case it did not diverge...
17            memcpy(img[i][j], black, 3); //...we set a black pixel
18        }
19        else { // If it diverged...
20            //...we set the color according to k (#iterations)
21            memcpy(img[i][j], getColor(k), 3);
22        }
23    }
24 }
```

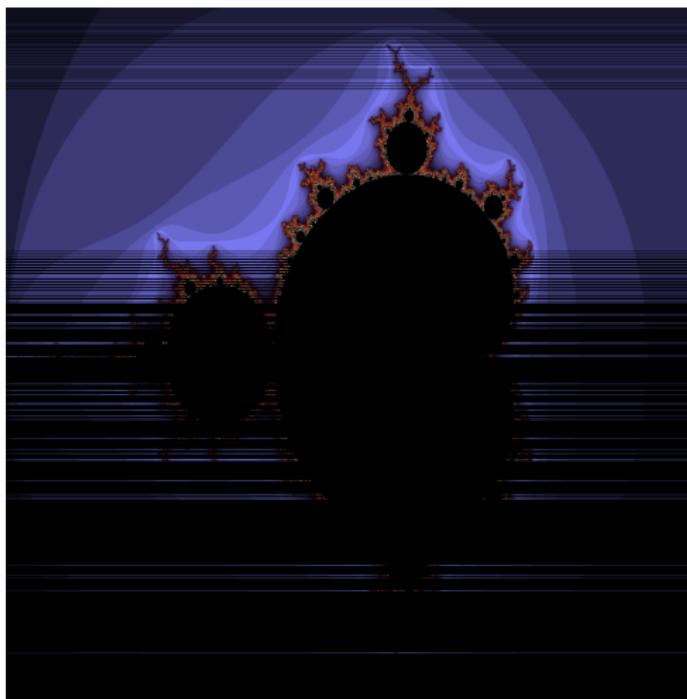
Mandelbrot: sequential code

```
1 void mandelbrot_seq(...) {
2     staticData *sd = assembleStaticData(...);
3
4     // Iterate on rows, sequentially
5     for (int i=0; i < yRes; ++i)
6     {
7         mandelbrot_kernel(i, sd);
8     }
9 }
```

Mandelbrot: futurized code

```
1 void mandelbrot_hpx (...) {
2
3     staticData *sd = assembleStaticData (...);
4
5     std::vector<hpx::future<void>> futures;
6     for (int i=0; i < yRes; ++i)
7     {
8         hpx::future<void> f = hpx::async(&mandelbrot_kernel, i, sd);
9         futures.push_back(f);
10    }
11
12    hpx::wait_all(futures);
13 }
```

Mandelbrot step by step



Summary

- ▶ Future exascale computing requires smart code.
- ▶ Resource awareness can be a way to achieve better performance.
- ▶ HPX has the potential to become a major runtime system for HPC, thanks to both its performance and programmability.

Thanks!

Summary

- ▶ Future exascale computing requires smart code.
- ▶ Resource awareness can be a way to achieve better performance.
- ▶ HPX has the potential to become a major runtime system for HPC, thanks to both its performance and programmability.

Thanks!