

Exc.: try the proof of uncertainty principle with  $K=A+B$ .  
 Heisenberg inequality on  $\mathbb{H} = L^2(\mathbb{R})$

$Q$  = position operator,  $(Q\psi)(x) = x \cdot \psi(x)$   
 $P$  = momentum operator,  $(P\psi)(x) = -i \frac{d}{dx} \psi(x)$

One can prove: if  $\psi$  is  $C_c^1(\mathbb{R})$ , then

$$[Q, P]\psi(x) = -ix \frac{d}{dx} \psi(x) + i \frac{d}{dx} (x\psi(x)) = i\psi(x) = i \text{Id} \psi(x).$$

These are called canonical commutation relations.

Heisenberg inequality reads as  $\frac{1}{2} \leq \Delta_\psi(Q) \Delta_\psi(P)$ .

### Two (last) postulates

- If  $|\psi\rangle$  is the state of your quantum system and the observable  $A$  is measured with outcome  $\lambda \in \sigma(A)$ , the state after the measurement is described by  $|P_\lambda \psi\rangle / \|P_\lambda \psi\|$  with  $P_\lambda: \mathbb{H} \rightarrow \mathbb{H}$  the orthogonal proj. on  $\text{Eig}(\lambda, A)$ .
- If instead the system is closed (isolated) the evolution of a state  $|\psi_t\rangle$  from time  $t_0$  to time  $t_1$  is described by a unitary  $U(t_0, t_1)$  s.t.  $|\psi_{t_1}\rangle = U(t_0, t_1) |\psi_{t_0}\rangle$ .

An observable  $H$  is the hamiltonian of a system if  $U(t_0, t_1) = e^{-i(t_1-t_0)H}$ .

Assuming that  $H$  does not depend on  $t$ , one can write  $|\psi_t\rangle = e^{-itH} |\psi_0\rangle$ .  
 $\partial_t |\psi_t\rangle = -iH |\psi_t\rangle \Rightarrow i\partial_t |\psi_t\rangle = H |\psi_t\rangle$ , Schrödinger's equation.

### Mixed states

Remember:  $|\psi\rangle = a|\psi_0\rangle + b|\psi_1\rangle$  is a superposition.

Idea:  $(p_i)_{i=1}^N$  classical probability,  $(|\psi_i\rangle)_{i=1}^N$  state vectors.

Density operator:  $\rho = \sum_i p_i |\psi_i\rangle \langle \psi_i|$  if  $\langle \psi_i | \psi_j \rangle = \delta_{ij}$ .

Def.: a mixed state on a system  $\mathbb{H}$  is described by any density operator  $\rho: \mathbb{H} \rightarrow \mathbb{H}$  s.t.

- is self-adjoint; • is non-negative; • has unit trace.

We write  $\mathcal{D}(\mathbb{H}) = \{ \rho: \mathbb{H} \rightarrow \mathbb{H} \mid \rho^* = \rho, \rho \geq 0, \text{Tr}(\rho) = 1 \}$ .

Remark: •  $\mathcal{D}(\mathbb{H})$  is convex;

- if  $|\psi\rangle \in \mathbb{H}$  is a (pure) state vector,  $\rho = |\psi\rangle \langle \psi| \in \mathcal{D}(\mathbb{H})$ .
- if  $|\varphi\rangle \in \mathbb{R}|\psi\rangle$  ( $\exists \alpha \in \mathbb{R}$  s.t.  $e^{i\alpha} |\varphi\rangle = |\psi\rangle$ ),  
 $|\psi\rangle \langle \psi| = |\varphi\rangle \langle \varphi|$ ;
- if  $U: \mathbb{H} \rightarrow \mathbb{H}$  is unitary, then  $\forall \rho \in \mathcal{D}(\mathbb{H})$   
 $U\rho U^* \in \mathcal{D}(\mathbb{H})$ .

Theorem: if  $\rho \in \mathcal{D}(\mathbb{H})$ ,  $\dim(\mathbb{H}) < +\infty$ , then

- $\exists (p_i)_{i=1}^n, p_i \in [0, 1], \sum_i p_i = 1, (|\psi_i\rangle)_{i=1}^n$  ONB of  $\mathbb{H}$  s.t.  
 $\rho = \sum_i p_i |\psi_i\rangle \langle \psi_i|$ ;
- $\rho^2 \leq \rho$  as quadratic forms, with  $=$  iff  $\rho$  is pure;
- $\|\rho\| \leq 1$  " " " " " " (exc.).

Proof: apply spectral theorem to  $\rho: (|\psi_{j,\alpha}\rangle)_{j,\alpha}$  ONB so that

$$\rho = \sum_j \lambda_j \sum_\alpha |\psi_{j,\alpha}\rangle \langle \psi_{j,\alpha}|, \{ \lambda_j \}_j = \sigma(\rho). \text{ Up to renumbering, } |\psi_{j,\alpha}\rangle \rightsquigarrow |\psi_i\rangle, \lambda_j \rightsquigarrow p_i.$$

$$\rho = \sum_i p_i |\psi_i\rangle \langle \psi_i| \Rightarrow \rho^2 = \sum_i p_i^2 |\psi_i\rangle \langle \psi_i| \leq \sum_i p_i |\psi_i\rangle \langle \psi_i| = \rho$$

because  $p_i \in [0, 1] \Rightarrow p_i^2 \leq p_i; \iff p_i \in \{0, 1\} \forall i$ , wlog  $p_1 = 1 \Rightarrow \rho = |\psi_1\rangle \langle \psi_1|$ .  $\square$

Postulates for mixed states:

- given  $A$  observable, its expectation over a mixed state  $\rho$  is  $\text{Tr}(A\rho) = \sum_i p_i \langle A \rangle_{\psi_i}$ , where  $\rho = \sum_i p_i |\psi_i\rangle \langle \psi_i|$ ,  $|\psi_i\rangle$  ONB;
- the probability of observing  $\lambda \in \sigma(A)$  if system is in the state  $\rho$  is  $P_\rho(\lambda) = \text{Tr}(P_\lambda \rho) = \sum_i p_i P_{\psi_i}(\lambda)$ ;
- after measuring  $\lambda \in \sigma(A)$ , the state  $\rho$  is updated to  $\frac{P_\lambda \rho P_\lambda}{P_\rho(\lambda)}$ .

If  $A$  is measured but the outcome is not given the state  $\rho$  is updated to  $\tilde{\rho} = \sum_{\lambda \in \sigma(A)} P_\rho(\lambda) \cdot \left( \frac{P_\lambda \rho P_\lambda}{P_\rho(\lambda)} \right)$ .

- If the system is closed it evolves from time  $t_0$  to  $t_1$  according to a unitary  $U(t_0, t_1): \rho_{t_1} = U(t_0, t_1) \rho_{t_0} U^*(t_0, t_1)$ .

The Schrödinger's eq. associated to  $H$  is

$$i\partial_t \rho_t = [H, \rho_t].$$

- Uncertainty of  $A$  over  $\rho$  is  $\Delta_\rho(A) = (\langle (A - \langle A \rangle_\rho \text{Id})^2 \rangle_\rho)^{1/2}$ .

Exc.: Heisenberg inequality for mixed states?

If  $\rho \in \mathcal{D}(\mathbb{H})$  is represented as  $\rho = \sum_{i=1}^m q_i |\psi_i\rangle \langle \psi_i|$ ,  $|\psi_i\rangle$  state vectors,  $q_i > 0$ , but also  $\rho = \sum_{j=1}^m p_j |\psi_j\rangle \langle \psi_j|$ ,  $p_j > 0$ ,  $(|\psi_j\rangle)_{j=1}^m$  ONB.

Then  $m \geq n$  and there exists  $U \in \mathbb{C}^{m \times m}$  s.t.  $UU^* = \text{Id}$

$$\text{with } \sqrt{q_i} |\psi_i\rangle = \sum_{j=1}^m U_{ij} \sqrt{p_j} |\psi_j\rangle.$$

Hint:  $U_{ij} = \frac{\sqrt{q_i} \langle \psi_j | \psi_i \rangle}{\sqrt{p_j}}$  for  $i=1, \dots, m, j=1, \dots, m$ .

Exc.: if  $\rho, \rho' \in \mathcal{D}(\mathbb{H})$  s.t.  $\langle A \rangle_\rho = \langle A \rangle_{\rho'} \forall A$  obs. then  $\rho = \rho'$ .

Hint:  $\text{Tr}(A\rho) = \text{Tr}(A\rho') \Rightarrow \text{Tr}(A(\rho - \rho')) = 0$ .